

# T21WN

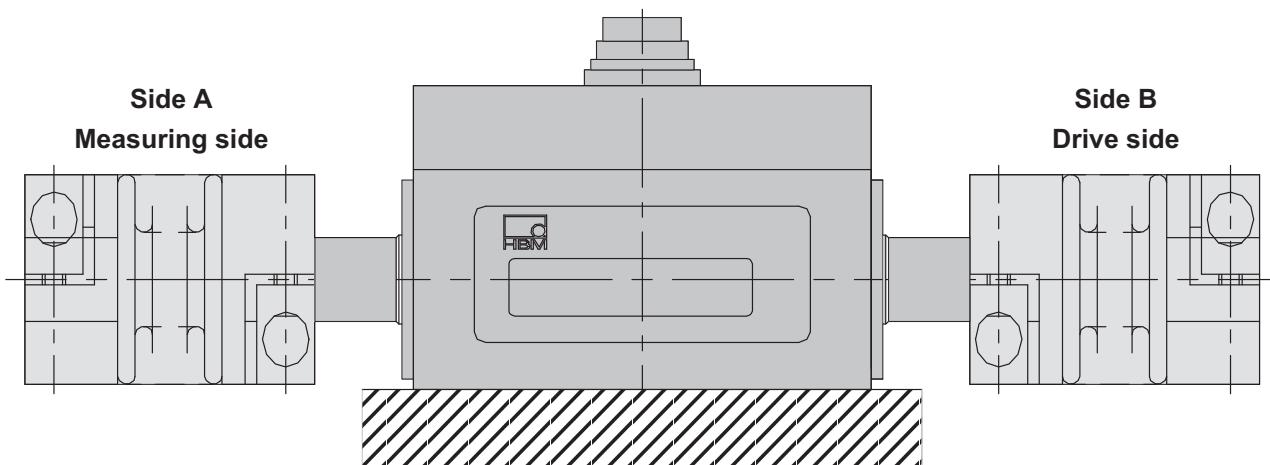
## Torque transducers



### Special features

- Nominal (rated) torques 0.1 N·m, 0.2 N·m, 0.5 N·m, 1 N·m, 2 N·m, 5 N·m, 10 N·m, 20 N·m, 50 N·m, 100 N·m, 200 N·m
- Non-linearity including hysteresis  $\leq 0.1\%$
- Non-contacting transmission of measured values
- High speeds for angle of rotation measurements up to 20,000 rpm
- Cylindrical shaft ends for friction fits
- Integrated measurement system for rotational speed and angle of rotation
- Torque output signal  $\pm 10$  V, 10 kHz  $\pm 5$  kHz

### Installation example with bellows couplings



Two of the couplings provided are needed for this example

## Specifications for T21WN

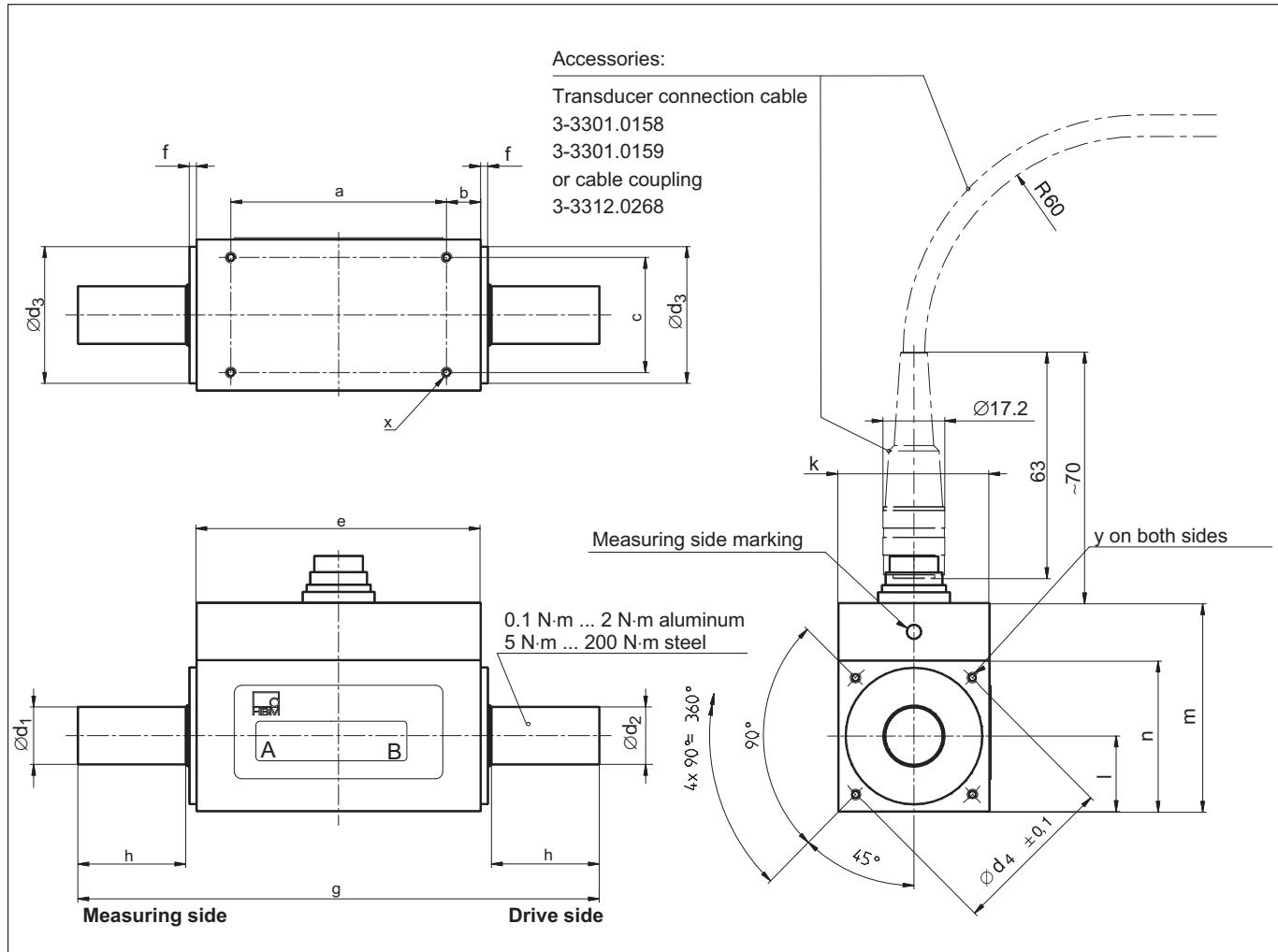
Type	T21WN																		
Accuracy class	0.2																		
<b>Nominal (rated) torque <math>M_{\text{nom}}</math></b>	N·m	0.1	0.2	0.5	1	2	5	10	20	50	100	200							
<b>Nominal (rated) rotational speed</b>	rpm	20,000				19,000				13,500									
<b>Non-linearity including hysteresis relative to the nominal (rated) sensitivity</b>	%	$<\pm 0.1$																	
<b>Rel. standard deviation of repeatability</b> per DIN 1319 relative to the variation of the output signal	%	$<\pm 0.05$																	
<b>Temperature effect per 10 K in the nominal (rated) temperature range</b>																			
on the output signal relative to the actual value of the signal span																			
Frequency output	%	$<\pm 0.1$																	
Voltage output	%	$\leq \pm 0.1$																	
on the zero signal relative to the nominal (rated) sensitivity																			
Frequency output	%	$<\pm 0.2$																	
Voltage output	%	$<\pm 0.2$																	
<b>Nominal (rated) sensitivity</b> (nominal (rated) signal range between torque = zero and nominal (rated) torque)																			
<b>Frequency output 10 kHz</b>	kHz	5																	
<b>Voltage output</b>	V	10																	
<b>Sensitivity tolerance</b> (deviation of actual output quantity at $M_{\text{nom}}$ from the nominal (rated) signal range)	%	$\pm 0.2$																	
<b>Nominal output signal</b>																			
<b>Frequency output (RS422, 5V symmetrical)</b>																			
with positive nominal (rated) torque	kHz	15																	
with negative nominal (rated) torque	kHz	5																	
<b>Voltage output</b>																			
with positive nominal (rated) torque	V	+10																	
with negative nominal (rated) torque	V	-10																	
<b>Load resistance</b>	MΩ	> 1																	
<b>Long-term drift over 48 h</b>	mV	$<\pm 50$																	
<b>Cut-off frequency (-3 dB)</b>	kHz	1																	
<b>Residual ripple (voltage output)</b>	mV <sub>ss</sub>	$< 100$																	
<b>Group delay</b>	ms	$< 1.0$																	
<b>Maximum modulation range</b>																			
Frequency output	kHz	3.7 ... 16.3																	
Voltage output	V	-11 ... +11																	
<b>Resolution</b>																			
Frequency signal	Hz	0.19																	
Voltage signal	mV	0.38																	
<b>Energy supply</b>																			
Nominal (rated) supply voltage (safety extra-low voltage (SELV))	V (DC)	10 ... 28.8																	
Calibration signal triggering	V	5 ... 24																	
Current consumption in measuring mode	A	with $U_b$ 12V $< 0.2$																	
Nominal (rated) power consumption	W	$< 2.4$																	
Permissible residual ripple of supply voltage	mV <sub>ss</sub>	200																	
<b>Calibration signal</b>	V	$+10 \pm 0.2\%$																	
<b>Output signal at torque = zero</b>	V	0 $\pm 0.05$																	
	Hz	10,000 $\pm 50$																	

Nominal (rated) torque M <sub>nom</sub>	N·m	0.1	0.2	0.5	1	2	5	10	20	50	100	200
<b>Measurement system for rotational speed/angle of rotation</b>												
<b>Measurement system</b>	Number											Optical
<b>Pulses per revolution</b>	V											360
<b>Output signal</b>	rpm											5 (unbalanced); two square wave signals phase shifted by approx. 90°
<b>Minimum rotational speed for sufficient pulse stability</b>	kΩ											0
<b>Load resistance</b>	μs											>10
<b>Group delay</b>												<3
												for 1.5 m cable between T21WN and VK20A junction box (without VK20A, the group delay is dependent on the connected impedance / cable & analysis device)
<b>Max. measurable rotational speed</b>	rpm											20,000 <sup>1)</sup>
<b>General information</b>												
<b>EMC</b>												
<b>Immunity to interference</b> (per EN61326-1, table A.1)	V/m											10
Electromagnetic field	A/m											30
Magnetic field												
Electrostatic discharge (ESD)	kV											4
Contact discharge												
Air discharge	kV											4
Fast transients (burst)	kV											2
Impulse voltage (surge)	kV											1
Conducted interference	V											10
<b>Emission</b> (per EN 61326-1, table 3)												
RFI voltage												Class B
RFI power												Class B
RFI field strength												Class B
<b>Degree of protection per EN 60 529</b>												IP40
<b>Weight, approx.</b>	kg											0.17
<b>Nominal (rated) temperature range</b>	°C											+5 ... +45
<b>Operating temperature range</b>	°C											0 ... +60
<b>Storage temperature range</b>	°C											-5 ... +70
<b>Mechanical shock and impact testing per EN 60068-2-27; IEC 68-2-27-1987</b>												
Number	n											1000
Duration	ms											3
Acceleration (half sine)	m/s <sup>2</sup>											650
<b>Vibration testing per EN 60068-2-6: IEC 68-2-6-1982</b>												
Frequency range	Hz											5 ... 65
Duration	h											1.5
Acceleration (amplitude)	m/s <sup>2</sup>											50
<b>Load limits<sup>2)</sup></b>												
<b>Torque limit relative to M<sub>nom</sub></b>	%											200 <sup>3)</sup>
<b>Breaking torque relative to M<sub>nom</sub></b>	%											> 280
<b>Longitudinal limit force</b>	kN	0.2	0.34	0.5	1.1	1.75	2.75	5.3	7.6	12.5		
<b>Lateral limit force</b>	N	3.6	5.7	8.3	18.2	29	46	88	127	207		
<b>Bending moment limit</b>	N·m	0.12	0.23	0.4	0.93	1.9	3.7	10	17	36		
<b>Oscillation bandwidth per DIN 50 100 (peak-to-peak)<sup>4)</sup></b>	%											80

Nominal (rated) torque $M_{\text{nom}}$	N·m	0.1	0.2	0.5	1	2	5	10	20	50	100	200
<b>Mechanical values</b>												
Torsional stiffness $c_T$	kN·m/rad		0.03		0.05	0.07	0.91	1.9	3.25	14	21.9	32.6
Torsion angle at $M_{\text{nom}}$	degrees	0.2	0.38	0.96	1.1	1.7	0.32	0.3	0.35	0.2	0.26	0.35
Max. limits for relative shaft vibration (peak-to-peak) <sup>5)</sup>	µm											
Effective vibration rate in the enclosure area per VDI 2056	mm/s											
Mass moment of inertia of the rotor (around rotary axis) with rotational speed measuring system ( $\times 10^{-3}$ )	gm <sup>2</sup>		0.06		0.063	0.068	6.10	6.13	6.23	53.7	54.6	57.2
Balance quality level per DIN ISO 1940	-											

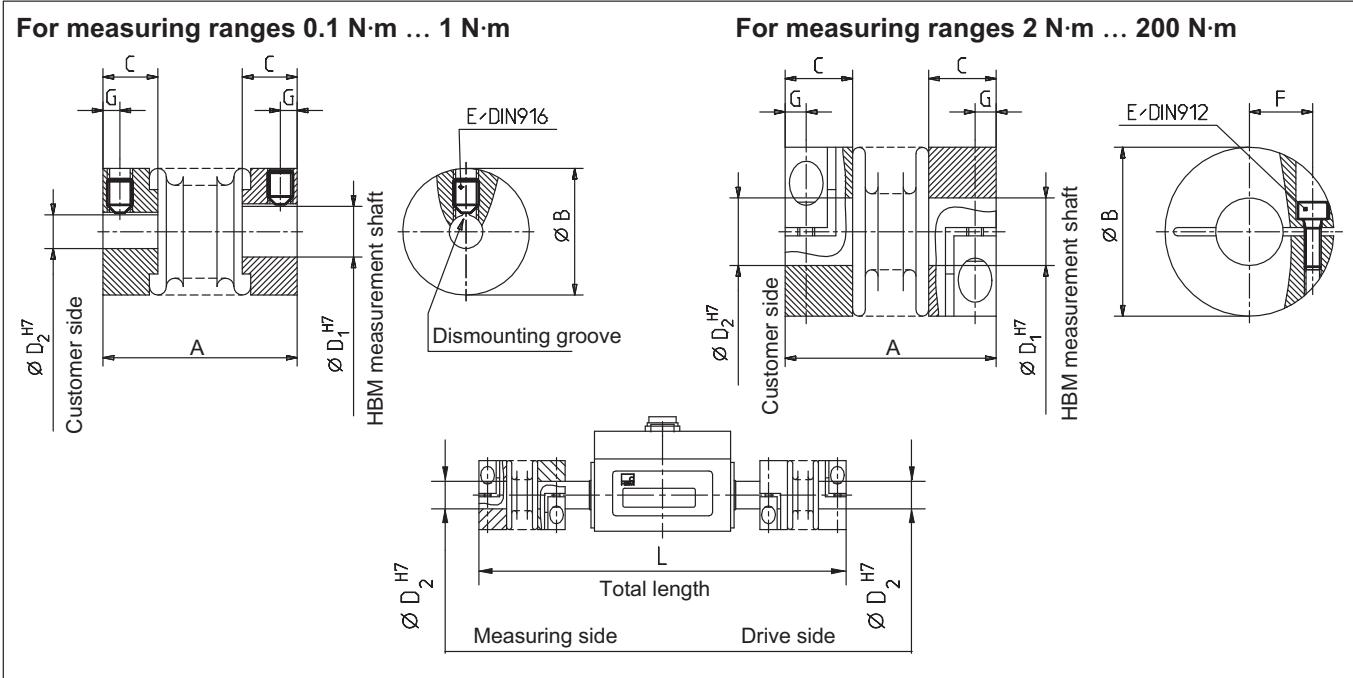
- 1) Dependent on the nominal (rated) torque
- 2) Each type of irregular stress (bending moment, lateral or longitudinal force, exceeding nominal (rated) torque) can only be permitted up to its specified static load limit and provided none of the others can occur at the same time. If this condition is not met, the limit values must be reduced. If 30% of the bending limit moment and lateral limit force occur at the same time, only 40% of the axial limit force is permissible and the nominal (rated) torque must not be exceeded. The permissible bending moments, longitudinal forces and lateral forces can affect the measurement result by approx. 1 % of the nominal (rated) torque.
- 3) Note the maximum torque ( $T_{K\max}$ ) of the coupling.
- 4) The nominal (rated) torque must not be exceeded.
- 5) Relative undulations, following DIN 45670/VDI 2059.

## Dimensions of T21WN



Measuring range (N·m)	Dimensions (in mm)																
	a	b	c	$e_{\pm 1}$	f	g	h	$k_{\pm 1}$	I	$m_{\pm 1}$	n	$\varnothing d_{1g6}$	$\varnothing d_{2g6}$	$\varnothing d_{3-0.1}$	$\varnothing d_{4 \pm 0.1}$	y	x
0.1	40	11	22	62	2	95	14	28	14	54	30	6	8	27	32	M3/6 deep	M3/5 deep
0.2	40	11	22	62	2	95	14	28	14	54	30	6	8	27	32	M3/6 deep	M3/5 deep
0.5	40	11	22	62	2	95	14	28	14	54	30	6	8	27	32	M3/6 deep	M3/5 deep
1	40	11	22	62	2	95	14	28	14	54	30	6	8	27	32	M3/6 deep	M3/5 deep
2	40	11	22	62	2	95	14	28	14	54	30	6	8	27	32	M3/6 deep	M3/5 deep
5	60	9.5	32	79	2	145	30	42	21	58	42	16	16	38	46	M3/6 deep	M3/6 deep
10	60	9.5	32	79	2	145	30	42	21	58	42	16	16	38	46	M3/6 deep	M3/6 deep
20	60	9.5	32	79	2	145	30	42	21	58	42	16	16	38	46	M3/6 deep	M3/6 deep
50	42	15	40	72	3	170	45	56	28	73	56	26	26	54	65	M4/8 deep	M4/8 deep
100	42	15	40	72	3	170	45	56	28	73	56	26	26	54	65	M4/8 deep	M4/8 deep
200	42	15	40	72	3	170	45	56	28	73	56	26	26	54	65	M4/8 deep	M4/8 deep

## Bellows couplings



## Dimensions

Measuring range (N·m)	Part no.	A	$\emptyset B$	C	Dimensions in mm (1 mm = 0.03937 inches)						
					$\emptyset D_1$ Measuring side T21WN	Drive side T21WN	$\emptyset D_2$ Variable from-to	E	F	G	L
0.1											
0.2	3-4412.0001	23.1	15	6.5	6	8	3-9	M3	-	2	128
0.5											
1	3-4412.0002	25.1	15	6.5	6	8	3-9	M3	-	2	132
2	3-4412.0003	40.1	25	13	6	8	3-12.7	M3	8	4	149
5											
10	3-4412.0004	50.1	40	16	16	16	5-22	M4	15	5	213
20	3-4412.0005	69.2	56	21	16	16	10-32	M6	19	7.5	241
50	3-4412.0006	80.2	66	23.5	26	26	12-32	M8	23	9.5	283
100	3-4412.0007	93.2	82	28	26	26	19-40	M10	27	11	300
200	3-4412.0008	109.2	110	35	26	26	24-56	M12	39	13	318

When ordering, please specify: connection holes D<sub>2</sub> as requested by the customer within specified limits; boring tolerance H7.

When using just **one** bellows coupling, specify the mounting side of the coupling:

**Measuring side = 6 mm / drive side = 8 mm**

## Specifications

Measuring range (N·m)	Torque coupling T <sub>Kmax</sub> (N·m)	Mass moment of inertia (kg·cm <sup>2</sup> )	Weight (g)	Torsional stiffness (kN·m/rad)	Maximum permitted offset			Spring stiffness		Material of hub and mounting ring	Tightening torque for clamping bolts (N·m)
					axial (mm) — — → ←	radial (mm) — — ↓	angular (degrees) — — ↙ ↘	axial (N/mm)	radial (N/mm)		
0.1	0.5	0.012	6	0.21	0.5	0.2	1.5	13.4	47.7	Aluminum	0.35
0.2					0.5	0.2	1.5	27.4	84.3		0.75
0.5					1	0.2	1.5	20.6	88		0.75
1					1.3	0.2	1.5	33.3	389		1.5
2					38	0.2	1.5	50	366		14
5					120	0.2	1.5	67	679		35
10					72	0.2	1.5	77	960		75
20					31	0.2	1.5	124	2940		120
50					1.2	0.2	1.5			Steel	
100					400	0.2	1.5				
200					1600	0.2	1.5				
					141	0.2	1.5				
					157	0.2	1.5				

## General instructions

- Do not tighten the clamping bolts of the couplings until the shafts are mounted in the coupling hubs!
- The bellows coupling must not be overstretched beyond the specified permissible flexibility limits.
- Drive and output shafts must be free from grease and burrs.
- Implement a tolerance of j6 for the shaft diameter to produce the preferred fit of H7/j6.

## Mounting position

The T21WN torque transducer can be operated with bellows couplings in any mounting position (horizontally, vertically or at an angle). When mounting vertically or at an angle, please make sure that the additional elements are adequately supported.

## Condition at the time of delivery

The couplings and the torque measurement shaft are delivered as separate items.

## Accessories for T21WN, to be ordered separately

- Transducer connection cable, 5 m long, ordering code. 3-3301.0158
- Transducer connection cable, 10 m long, ordering code 3-3301.0159
- Cable socket, 12-pin (binder), ordering code 3-3312.0268
- Junction box, ordering code 1-VK20A
- Bellows couplings

## Accessories for junction box VK20A, to be ordered separately

- Connection cable, 1.5 m long (D-Sub, 15-pin - free ends), ordering code 1-KAB151A-1.5
- Connection cable, 1.5 m long (SUBCON5 - free ends), ordering code 1-KAB152-1.5

Subject to modifications.

All product descriptions are for general information only. They are not to be understood as a guarantee of quality or durability.

**Hottinger Baldwin Messtechnik GmbH**

Im Tiefen See 45 · 64293 Darmstadt · Germany  
Tel. +49 6151 803-0 · Fax +49 6151 803-9100  
Email: [info@hbm.com](mailto:info@hbm.com) · [www.hbm.com](http://www.hbm.com)

**measure and predict with confidence**



B04777\_03\_E00\_01 HBM: public